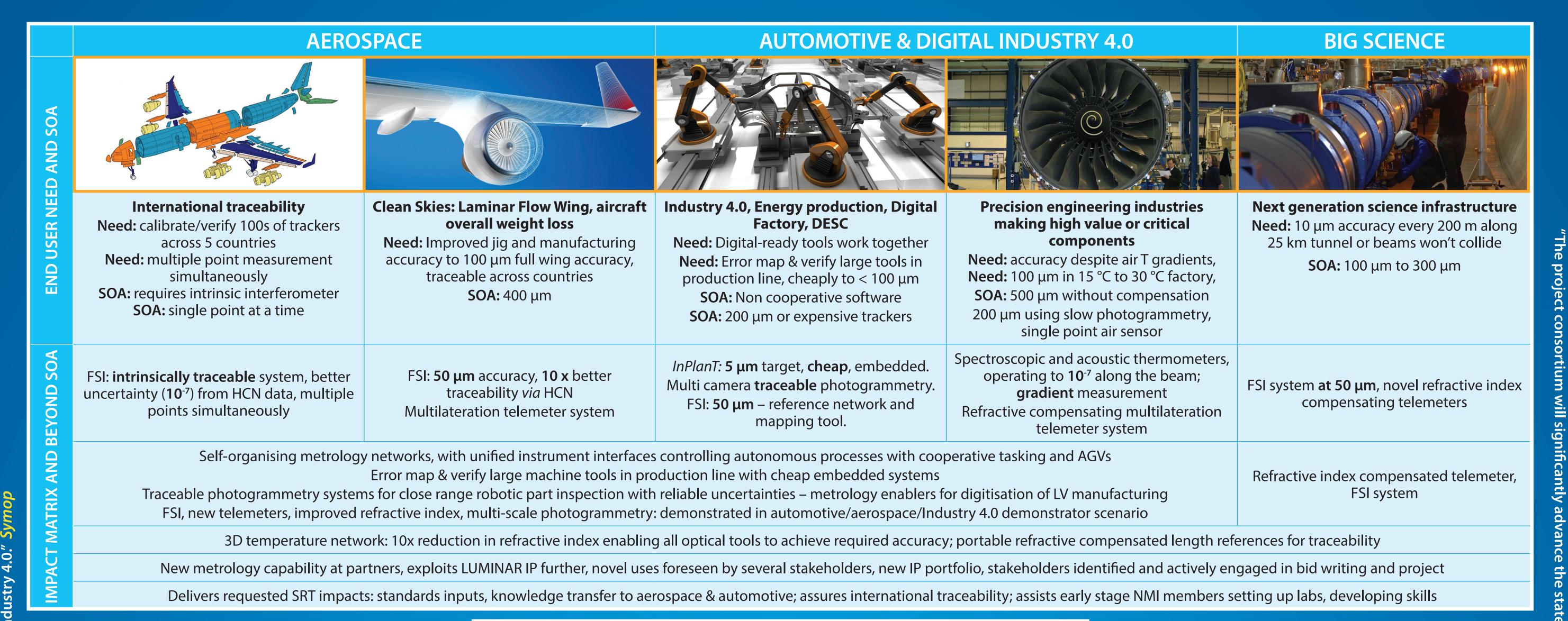
# Large Volume Applications

Metrology solutions needed to support research and Industry 4.0



#### WP3 - High accuracy refractive index

- 1. Spectroscopic thermometer prototype
  - High accuracy, 5 m to 50 m, based on molecular oxygen
- 2. Pulse-based acoustic thermometry and refractive index
  - (a) Time of flight systems: 2 m and 50 m variants (b) Continuous wave system, investigation of 3D temperature gradients
- 3. Comparison of systems in lab and real-world
- 3D index and reference length for LVM

#### WP2 - Novel techniques for medium/ large volumes

- (i-a) NMI-class 3D in-line inspection system
  - Robot compatible, with intelligent data processing
  - Industrial case study of aerospace/automotive part measurements
- (i-b) Industrial multi-camera for traceable 3D Providing absolute 3D coordinates
- (ii-a) Air index compensated multilateration 3D prototype
- Designed for accurate part fiducialisation
- (ii-b) Cheap multi-camera system for 3D in very large volumes

"We believe that the technologies planned for development in this EMPIR project have a high chance of success ... and that through their delivery, the project consortium will significantly advance the SOA of Large Volume Metrology. In particular we foresee several potential application areas for the technologies being developed".

5 signatories representing Airbus Engineering, Business Development, Laboratories & Test Centres, Data Capture, Structures (UK and France)

# **JRP Demonstrators**

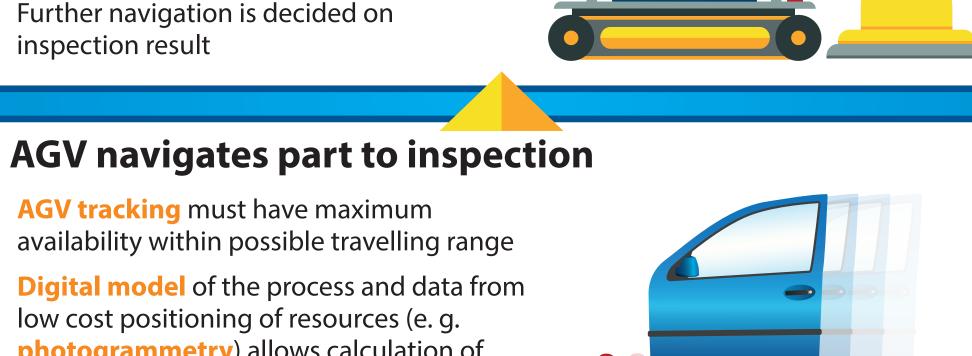
#### Intercomparison on refractive index

### Part is inspected

Inspection is either done with free-form scanners (preferred) or tactile sensors attached to a robot Robot is referenced either by **photogrammetry** 

or FSI depending on required uncertainty Measurement process is implemented to be regarded as traceable

Further navigation is decided on inspection result



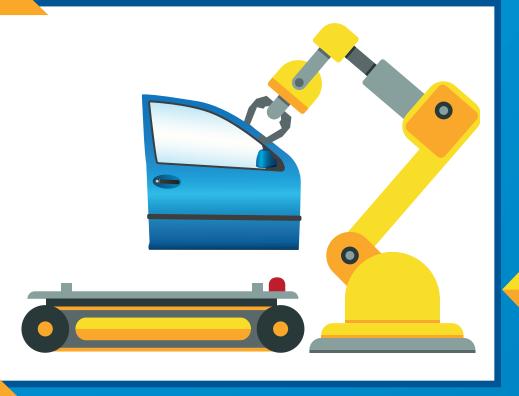
low cost positioning of resources (e.g. photogrammetry) allows calculation of optimal schedule and route to inspection

If the AGV tracking system fails, it can either be taken over by another available

positioning system or navigation continues by means of model-based prediction

#### **Part loaded onto AGV**

Robot is tracked by **Photogrammetry AGV tracking and Photogrammetry** are referenced to each other for seamless transition



## In situ machine tool metrology

- Embedded targets remain in machine, with laser optics in wrist.
- Automated error mapping.
- Online performance evaluation pre-,

past- manufacture of parts.

Intercomparison on photogrammetry systems

# WP1 – Improved FSI metrology

- 1. Develop multiple independent measuring system
  - Linear and saturated absorption HCN cells at different pressures Improved peak fitting
- 2. Comparison of cells and system

Absolute and relative spectroscopy Saturated spectroscopy Open access HCN data Integrate into FSI system

## WP4 - Process modelling and unified interfacing

- 1. Metrology oriented process and device models Cooperative network of instruments
- 2. Unified interfacing of LVM devices
- Open access interface, easily integrated into
- networks 3. Real-world auto/aero/digital Factory 4.0
- integrated demonstrator system AGV, laser trackers, refractive-compensated
- telemeters, photogrammetry, FSI All under a unified control interface, with
- cooperative tasking

Automated trans machine/trans robot transfer

## WP5 - Traceable large machine tool metrology

- 1. Improved optical targets
- 2. Low cost system embedded in large machine tool
- 3. Integrated with machine controller
  - Allows ongoing checks during production
- 4. Demonstrated on Fidia machine and another at **RWTH end of project demonstrator**

DISSEMINATION		IMPACT		
Exploitation	Knowledge transfer	Financial	Social	Environmental
<ul> <li>IP uptake by partners <ul> <li>Fidia, MapVision</li> </ul> </li> <li>Licensing to metrology companies: <ul> <li>e.g. Renishaw, Hexagon, Leica</li> </ul> </li> <li>IP list and exploitation plan</li> <li>NMI services &amp; consultancy</li> <li>Open access HCN data via MeP</li> <li>Unified instrument interface for Industry <ul> <li>4.0 metrology network</li> </ul> </li> </ul>	<ul> <li>Stakeholder committee</li> <li>JRP open website and sci-social media</li> <li>12+ major industrial LVM conferences</li> <li>2+ technical &amp; standards committees</li> <li>5+ open access journal papers</li> <li>2 trade articles (already one invite)</li> <li>NPL Dimensional Training Framework</li> <li>Training sessions at CMSC, 3DMC</li> <li>Major industrial demonstrator setup</li> <li>Industrial workshop at end of project</li> </ul>	<ul> <li>Critical to Laminar Flow Wing:         <ul> <li>Safeguards €2.3 trillion 2030 orders whilst complying with 2020 regulations;</li> </ul> </li> <li>Saves money on high value components         <ul> <li>€10k per day engine depreciation</li> <li>Reduced scrappage via in line self-checking of large machine tools</li> </ul> </li> </ul>	<ul> <li>Enables LHC successor to work (science jobs, new knowledge)</li> <li>Enables improved beam therapies for oncology</li> <li>Maintains EU advanced manufacturing advantage over USA and Asia:         <ul> <li>€498m EU engineering turnover,</li> <li>3.25m jobs</li> <li>EU has 36 % market share machine tools worldwide</li> <li>4.2 million EU jobs in aviation</li> </ul> </li> </ul>	<ul> <li>Benefits from estimated 100 kg lower aircraft weight from JRP outputs, per aircraft: <ul> <li>38.5 tonnes less CO<sub>2</sub> p.a.</li> <li>1.4 M litres of fuel saved p.a.</li> </ul> </li> <li>Enables manufacturing of small modular nuclear reactors (reducing CO<sub>2</sub>, NO<sub>x</sub>)</li> <li>Enables science for &gt;breakeven fusion reactors</li> </ul>







































































